

How to Write Fast Code

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Summer Research Project

- Preferred: undergraduate student
- Fulltime (40 hours/week), 3 months
- Pay: standard CMU (somewhere between 10 and 15/hour)
- Requirement: good standing in this class, overall GPA > 3.5
- Why?
 - Research experience, maybe even publication
 - Good for grad school



Today

How to get a fast DFT: FFTW (version 2.x)
 Focus on scalar code

References

- FFTW website
- M. Frigo: <u>A fast Fourier transform compiler</u>



- Locality of data access (reuse)
- Precomputing constants
- Fast basic blocks
- Adaptivity



Locality of data access (reuse)

- Blackboard
- Precomputing constants
- Fast basic blocks
- Adaptivity



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Precomputing Constants

The "twiddle" matrix T produces multiplications by constants that are sines and cosines:

```
y[i] = sin(i \cdot pi/128) \cdot x[i]
```

```
Very expensive! (remember HW 2)
```

Solution:

- Precompute once and store in table
- Reuse many times
- Assumes transform is used many times (what if not?)



- Locality of data access (reuse)
- Precomputing constants
- Fast basic blocks
 - The FFTW codelet generator
- Adaptivity



Basic Block Optimizations for FFTs

Problem: similar to MMM

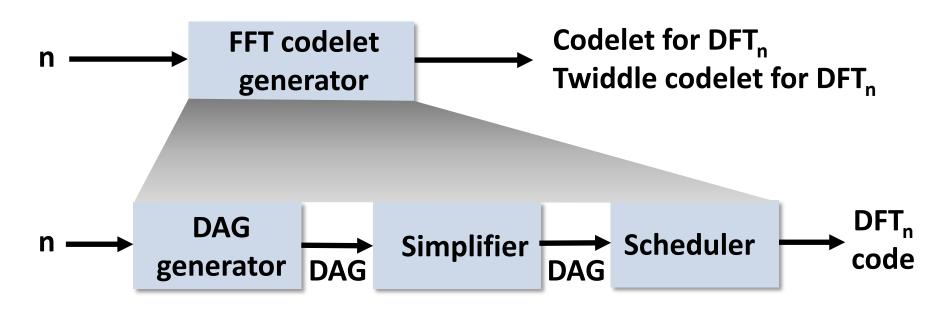
- We do not want to recurse all the way to n = 2
- Infrastructure produces overhead = destroys performance.

Solution:

- Unrolled DFT code for fixed small sizes (≤ 32 say).
 In FFTW called codelets
- Optimization for these blocks is much harder than for the micro MMMs in MMM
- Again, compilers often don't do a good job on unrolled code
 - Doing it by hand you get a crisis (62 functions! Why 62?)
- Solution: Code generator/optimizer for small sizes



FFTW Codelet Generator



DAG: directed acyclic graph

- Represents a DFT algorithm (the dataflow)
- Nodes: load, store, adds, mults by constant

Give example on blackboard

DAG Generator

Knows FFTs: Cooley-Tukey, split-radix, Good-Thomas, Rader, represented in sum notation

$$y_{n_2j_1+j_2} = \sum_{k_1=0}^{n_1-1} \left(\omega_n^{j_2k_1}\right) \left(\sum_{k_2=0}^{n_2-1} x_{n_1k_2+k_1} \omega_{n_2}^{j_2k_2}\right) \omega_{n_1}^{j_1k_1}$$

- For given n, suitable FFTs are recursively applied to yield n (real) expression trees for y₀, ..., y_{n-1}
- Trees are fused to an (unoptimized) DAG



Simplifier

Applies:

- algebraic transformations
- common subexpression elimination (CSE)
- DFT-specific optimizations

Algebraic transformations

- Simplify mults by 0, 1, -1
- Distributivity law: kx + ky = k(x + y), kx + lx = (k + l)x
 May destroy common subexpressions and thus increase op count!
- Canonicalization: (x-y), (y-x) to (x-y), -(x-y)

CSE: standard

• E.g., two occurrences of 2x+y: assign new temporary variable

DFT specific optimizations

- All numeric constants are made positive
- Reason: constants need to be loaded into registers, too
- CSE also on transposed DAG

Scheduler

- Determines in which sequence the DAG is unparsed to C (topological sort of the DAG)
 Goal: minimizer register spills
- If R registers are available, then a 2-power FFT needs at least Ω(nlog(n)/R) register spills [1]
 Same holds for a fully associative cache
- FFTW's scheduler achieves this (asymptotic) bound independent of R
- Sketch it on blackboard

[1] Hong and Kung: "I/O Complexity: The red-blue pebbling game"



Codelet Examples

- Notwiddle 2
- Notwiddle 3
- Twiddle 3
- Notwiddle 32

Techniques not seen before:

- Scoping (variables only defined where they occur) Purpose: simplifies dependency analysis
- Single static assignment (SSA) style: Each variable has only one single definition in the code Purpose: no artificial dependencies



- Locality of data access (reuse)
- Precomputing constants
- Fast basic blocks
- Adaptivity
 - Start on blackboard



Dynamic Programming (DP)

- An algorithmic technique to solve optimization problems
- Definition: DP solves an optimization problem by caching and reusing subproblem solutions (memoization) rather than recomputing them
- Well-suited for all divide-and-conquer algorithms with a degree of freedom in the divide step
- Inherent assumption: Best solution is independent of the context in which the problem has to be solved



DP for FFTs

- Goal: Find the best recursion strategy for a DFT of size 2^k, computed with the Cooley-Tukey FFT
- Assume the best recursions for sizes 2¹,...,2^{k-1} are already computed
- Split DFT 2^k in all k-1 possible ways and use the best recursions for the smaller DFTs.
- The fastest of these k-1 algorithms is the solution for 2^k
- Cost: (k-1)+(k-2)+...+1 = O(k²) for size 2^k





DP for FFTs (cont'd)

In FFTW: Essentially as described on the previous slide, except left DFT is of size ≤ 64 (since twiddle codelet)

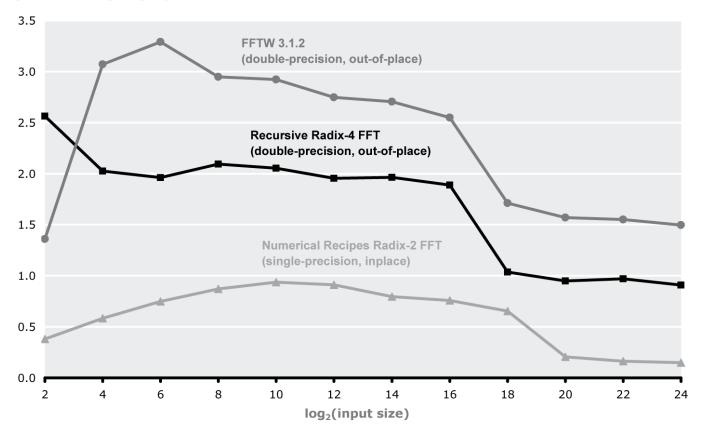
Does DP assumption hold for FFTs?

- Not clear. In particular the best FFT could depend on the stride.
- But works well in practice and is fast



Performance (Scalar Code)

DFT on 2.66 GHz Core2 Duo (32-bit Windows XP, Single Core, x87) performance [Gflop/s]



The code for radix-4 FFT is in the tutorial

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()	Electrical & Computer
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	MMM	Sparse MVM	DFT	
	Atlas	Sparsity/Bebop	FFTW	
Cache	Blocking	Blocking	recursive FFT,	
optimization		(rarely useful)	fusion of steps	
Register	Blocking	Blocking	Scheduling	
optimization		(sparse format)	small FFTs	
Optimized basic blocks	Unrolling, instruction ordering, scalar replacement, simplifications (for FFT)			
Other optimizations	_	_	Precomputation of constants	
Adaptivity	Search: blocking parameters	Search: register blocking size	Search: recursion strategy	